

# Band pass filter design

## Part 8. Compensating for inductor losses

### 1. Introduction

In Part 6 we looked at the effects of the inevitable losses in practical inductors. The higher circulating currents in the resonators towards the edges of the pass band cause increased power loss and a rounding of the frequency response. This Part presents a method for compensating for the degradation of the response caused by the inductor losses. The “q & k” design method is used, as described in Part 2 of this series. As will be seen, there is a price to be paid for the improved frequency response – the overall losses within the filter are deliberately increased.

### 2. Compensating for inductor losses

The losses in inductors can be compensated by a technique called “pre-distortion” which uses amended values for q & k. Tables of pre-distorted q & k values have been calculated for various inductor Q factors for a wide range of filter responses (Ref. 1). All of the inductors must have the same value and Q factor. It is unlikely that q & k values will be available for the Q of the inductor to be used, so the nearest tabulated Q value must be used or the values extrapolated. The tables also predict the overall loss of the filter.

The losses of the end resonators are absorbed into the input and output terminating resistors. In a two-resonator design this means that the pre-distorted values are the same as the standard q & k values. A two-resonator loss-compensated design was examined in Part 7.

The first filter we will examine is a three resonator Chebychev design with a pass band ripple of 0.1dB, with a centre frequency of 10MHz, a bandwidth of 500kHz using toroid inductors with an inductance of 1uH and a  $Q_L$  of 200. Chebychev designs with 0.1dB ripple are popular because of the almost flat response over the pass band.

Firstly we must calculate the value of the normalised unloaded resonator  $Q_0$  which is given by:-

$$Q_0 = \frac{Q_L}{Q_{BP}}$$

where  $Q_{BP}$  is the ratio of the filter frequency to the 3dB bandwidth

$$Q_{BP} = \frac{F_0}{F_{3dB BW}}$$

If  $Q_L = 200$ ,  $F_0 = 10\text{MHz}$  and  $F_{3dB BW} = 500\text{kHz}$ , then  $Q_{BP} = 20$  and so  $Q_0 = 10$ .

Table 1 contains normalised values of  $q_1$ ,  $k_{12}$ ,  $k_{23}$  and  $q_2$  (from Ref. 1) for a three resonator filter with a Chebychev response and with a pass band ripple of 0.1dB. Seven different values for  $Q_0$  are listed and so the  $Q_0$  closest to the calculated value must be used.

Looking at the  $Q_0$  column in Table 1, the closest tabulated value is 9.6. The predicted insertion loss is 3.2dB. The rest of the row gives the  $q_1$ ,  $k_{12}$ ,  $k_{23}$  and  $q_2$  values and are all that is necessary to design a pre-distorted filter. Notice that unless the filter is lossless, it is no longer symmetrical i.e.  $q_1$  is not equal to  $q_2$ , and  $k_{12}$  is not equal to  $k_{23}$ .

Qo	Insertion Loss (dB)	q1	k12	k23	q2
Lossless	0	1.4328	0.6618	0.6618	1.4328
28.7	0.9	1.2184	0.6539	0.6667	1.8511
14.3	2.0	1.1922	0.6311	0.6807	2.0522
9.6	3.2	1.1907	0.6029	0.6966	2.2158
7.2	4.6	1.2013	0.5703	0.7138	2.3595
5.7	6.2	1.2202	0.5329	0.7325	2.4887
4.8	8.2	1.2461	0.4897	0.7527	2.6045
4.1	10.8	1.2789	0.4380	0.7751	2.7052

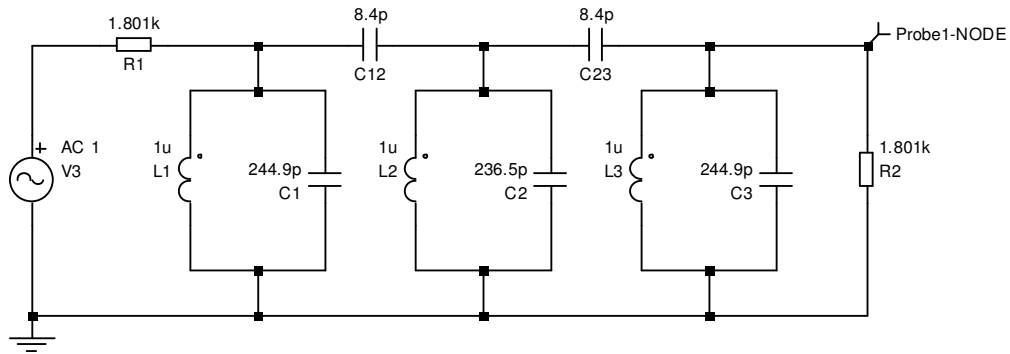
**Table 1. Lossless and pre-distorted q & k values for Chebychev 0.1dB 3-resonator filter**

The calculations are shown below. Qo is 10 for the filter under consideration – the pre-computed tables have Qo = 9.6 as the nearest value and so the pre-distorted values for that Qo are used. A simple spreadsheet can be set up to make the calculations.

Parameter	Formula	Lossless	QL = 200
Fo	Filter centre frequency	10MHz	10MHz
F <sub>3dB BW</sub>	3dB bandwidth	500kHz	500kHz
L	Chosen inductor value (all inductors)	1 uH	1 uH
QL	Inductor Q at Fo	Infinity	200
Q <sub>BP</sub>	$Q_{BP} = F_o / F_{3dB BW}$	20	20
Qo	$Q_o = Q_L / Q_{BP}$	Infinity	10 (9.6 used)
q1	From Table 1	1.4328	1.1907
k12	From Table 1	0.6618	0.6029
K23	From Table 1	0.6618	0.6966
q2	From Table 1	1.4328	2.2158
Cnode	$C_{node} = 1 / ((2\pi F_o)^2 L)$	253.3 pF	253.3 pF
R <sub>TERM1</sub>	$R_{TERM1} = 2\pi F_o L Q_{BP} q1$	1,801 Ohms	1,496 Ohms
R <sub>TERM2</sub>	$R_{TERM2} = 2\pi F_o L Q_{BP} q2$	1,801 Ohms	2,784 Ohms
Rs	$R_s = 2\pi F_o L / Q_L$	0	0.314 Ohms
Rp	$R_p = Q_L / (2\pi F_o C_{node})$	Infinity	12,566 Ohms
R1	$R1 = R_p R_{TERM1} / (R_p - R_{TERM1})$	1,801 Ohms	1,699 Ohms
C1	$C1 = C_{node} - C12$	244.9 pF	245.7 pF
C12	$C12 = C_{node} k12 / Q_{BP}$	8.4 pF	7.6 pF
C2	$C2 = C_{node} - C12 - C23$	23.5 pF	236.8 pF
C23	$C23 = C_{node} k23 / Q_{BP}$	8.4 pF	8.8 pF
C3	$C3 = C_{node} - C23$	244.9 pF	245.7 pF
R2	$R2 = R_p R_{TERM2} / (R_p - R_{TERM2})$	1,801 Ohms	3,577 Ohms

**Table 2. Formulae and component values for loss less and pre-distorted filter**

The circuit diagram of the loss less filter, drawn using a SPICE simulator (Ref. 2) is shown in Fig 1.

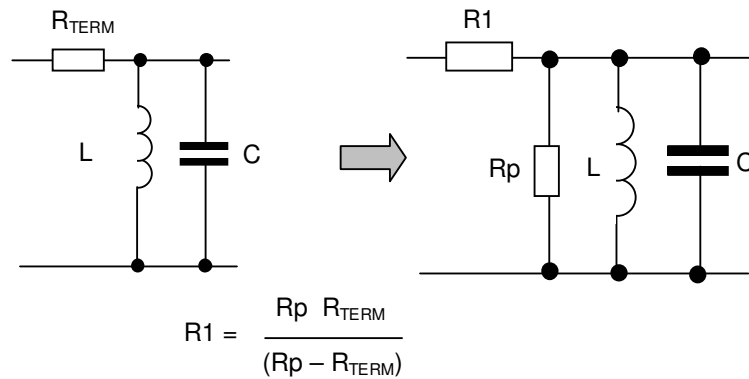


**Fig. 1. Lossless filter**

In Table 2, R1 and R2 are the input and output terminating resistors and the values have been calculated to give the required termination resistances when the loss resistances of the input and output resonators are taken into account – see part 6 of this series. The loss in an inductor can be represented by a series resistance  $R_s$ . When an inductor forms part of a resonator (or tuned circuit), then at the resonant frequency the loss can instead be represented by a parallel resistance  $R_p$ , with a value given by

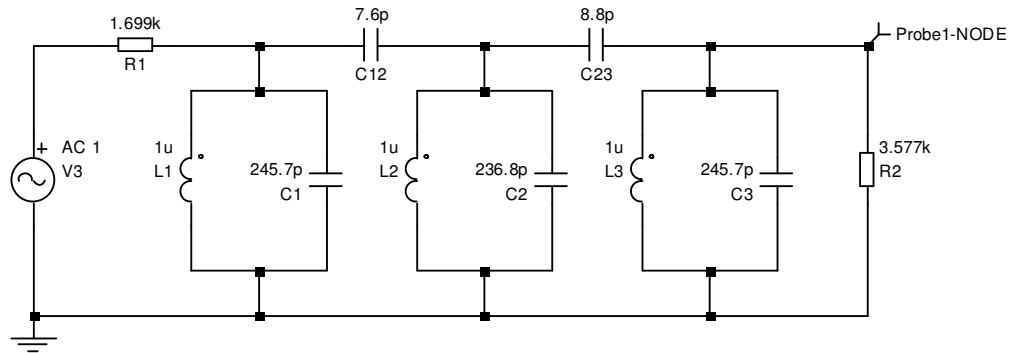
$$R_p = \frac{L}{C R_s}$$

The filter requires specific input and output terminating resistances. This is made up by the parallel loss resistance of the input and output resonators in parallel with the actual physical input and output resistors



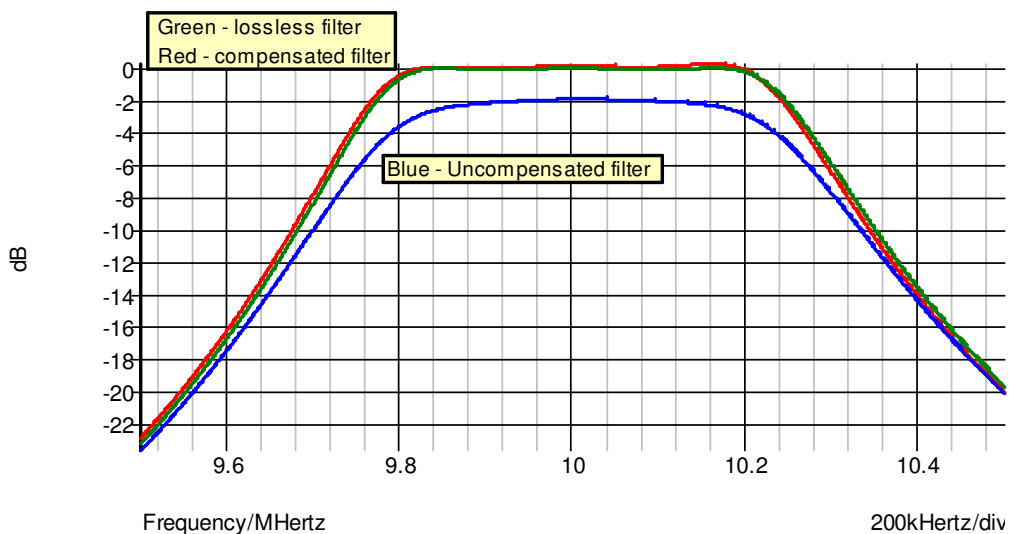
**Fig 2. Compensation for loss in the end resonators**

The final filter is shown in Fig 2.



**Fig. 3. Pre-distorted Chebyshev 0.1dB filter for  $Q_L = 200$**

The insertion losses of the loss less filter in Fig. 1, the uncompensated filter and the compensated filter in Fig 2 are shown in Fig 3.



**Fig. 4. Filter insertion losses**

Fig. 4 shows that the response of the pre-distorted filter and it is almost identical to the loss less filter. The uncompensated filter has more loss and shows the rounded response towards the extremes of the pass band. Notice that the pre-distorted filter response is to all intents identical to the loss less design, yet the insertion loss is predicted to be 3.2dB. How can this be? The reason is simply that the terminating resistances are no longer equal and there is a voltage gain equal to the square root of these terminating resistors namely 3.0dB, so the difference is only 0.2dB.

### 3. Conclusion

The degradation of the frequency response of band pass filters caused by inductor losses can be compensated by pre-distortion. The output voltage of the pre-distorted filter may still be almost identical to that of a loss less design due to the higher output terminating resistance.

#### 4. References

1. Anatol I. Zverev, "Handbook of Filter Synthesis", Wiley Interscience. This book was first published in 1967 and is regarded as a classic and is quoted as a reference in a great many articles about filter design. It is available now in paperback form. Personally, I find it quite hard going.
2. [www.simetrix.co.uk](http://www.simetrix.co.uk) An excellent free evaluation version of SPICE.